

Exploring the Security Boundary of Data Reconstruction via Neuron Exclusivity Analysis

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Threats of Data Reconstruction Attacks

"The Achilles Heel" of Privacy-Preserving Distributed Learning





Existing Attacks Solve the Gradient Matching Problem via Optimization

The Gradient Matching Problem



Attack Instances

- **DLG** [Zhu et al.; NIPS'19]: $d(G_i, \overline{G_i}) = ||G_i \overline{G_i}||_2$, L-BFGS;
- Inverting [Geiping et al.; NIPS'20]: $d(G_i, \overline{G_i}) = (1 \cos(G_i, \overline{G_i}))$, Adam;
- **GradInversion** [Yin et al.;CVPR'21]: BatchNorm statistics as the prior;

Distance Metric

Attacker's Knowledge

- 1. The Model Parameter (Θ)
- 2. The Average Gradient (\overline{G})
- 3. The NN Architecture (*f*)
- 4. The Batch Size (M)



Empirical Results and The Mysteries

• DLG Results (Batch Size M = 8, ResNet-56)



• Inverting Results (Batch Size M = 100, ResNet-32)



GradInversion Results



Original



batch size 4



batch size 16 Restored



batch size 48



Our Work Answers

- 1. How the separation from the average gradient is possible?
- 2. What factors influences data reconstruction attacks?



Exploiting the ExANs in ReLU Networks

**ExAN* = Exclusively Activated Neurons (dubbed by us)

O Def.: ExAN at the i-th ReLU layer

$$\sum_{m=1}^{M} [A_i^m]_j = 1$$

$$activation pattern$$

• First ReLU Layer

λ

 $A_1^1 = \begin{pmatrix} 1 & 0 & 1 \end{pmatrix}$ (0) $A_1^2 = (0 \ 0 \ 1$ 1)

Second ReLU Layer

$$A_2^1 = \begin{pmatrix} 1 & 1 & 1 & 0 & 0 \end{pmatrix}$$
$$A_2^2 = \begin{pmatrix} 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$





- Property: Backward signals (dashed lines) only flow via
 - neurons activated in forward computation (solid lines)



Neuron Exclusivity Analysis on Data Reconstruction

Gradient Matching Problem -> Gradient Equation ${\color{black}\bullet}$

$$\min_{\{(X_m,Y_m)\}_{m=1}^M} d(\frac{1}{M} \nabla_{\Theta} \ell(f_{\Theta}(X_m), Y_m), \overline{G})$$

• Let's consider the (unbiased) **FCN**: $f(X; W_0, ..., W_H) = W_H D_H ... W_1 D_1 W_0 X$

$$\overline{G}_{i} = \sum_{c=1}^{K} \overline{g}_{c} \frac{\partial f_{c}}{\partial W_{i}} \xrightarrow{\text{nonlinearity}} \overline{g}_{c} = \begin{cases} p_{c} & \text{if } c \\ p_{c} - 1 & \text{if } p_{c} \\ p_{c} - 1 & \text{if } p_{c} \\ \end{pmatrix}$$

$$\frac{\partial f_{c}(X)}{\partial W_{i}} = (D_{i}W_{i-1} \dots W_{0}X)([W_{H}]_{c}^{T}D_{H} \dots W_{i+1}D_{i+1})$$



Main Results on Security Boundary

(Attack Side) When a mini-batch satisfies the following ExAN condition, all [#] the samples can be analytically reconstructed with provably low error.

In the last ReLU layer, each sample has \geq 2 ExANs => reconstructing \overline{g}_{c}^{m}

In the remaining ReLU layers, each sample has \geq 1 ExAN => reconstructing D_i^m

(**Defense Side**) When a mini-batch satisfies the following condition, there exists infinitely many batches which share the same gradients.

In the first ReLU layer, each sample has 0 ExAN => Impossibility of Reconstruction (due to infinitely many candidate solutions)





Reconstructing the Loss Vectors

- Inspecting the gradient equation of the last ReLU layer. \boldsymbol{M} $\left[\overline{G}_{H}\right]_{c} = \frac{1}{M}$
- **Observation I**: If the m-th sample has at least 2 ExANs at the last ReLU layer, there are always 2 more repetitive values in the ratio vector $[\overline{G}_H]_i/[\overline{G}_H]_k$, which equals to $\overline{g}_i^m/\overline{g}_k^m$.



$$\frac{1}{4}\sum_{m=1}^{\infty} \overline{g}_{c}^{m} f_{H-1}^{m}$$
(8)

- With the estimated ratios $\overline{g}_i^m / \overline{g}_k^m$
 - Determine the labels based on the signs.
 - Determine the range of \overline{g}_i^1 based on the constraints $\sum p_c = 1$



Reconstructing the Activation Patterns

layer, i.e., D_{i-1}^m



Observation II. If the m-th sample has 1 ExAN at the i-th layer, then **the non**vanishing gradients to the precedent layer indicate the ExANs at the (i-1)-th

> **Recursion**: If the (i-1)-th layer has at least one ExAN, the reconstruction can be done for the (i-2)-th layer ... until the first ReLU layer.

o The 1st ReLU o The 2nd ReLU $1 \ 0 \ 0) \ A_1^1$ $0 \quad 1 \quad 0$ $A_2^2 = (0)$





Extension to Deep ConvNets

1 × Gradient Matching Problem -> M × Feature Matching Problem

 X_m



$\arg\min\|\Phi(X_m)-\hat{\Phi}_m\|$

Defense Side Results

A Moderate Architectural Change for <u>Exclusivity Elimination</u>



• Infinitely Many Solutions when $M \leq d_1$



Combo with Other Obfuscation (e.g. DPSGD)



More Evaluation Results









More Evaluation Results

 Precise reconstruction of almost however large batch when sufficient exclusivity is satisfied

> Facescrub **3-Layer FCN** Batch Size 128









Conclusions and Future Directions





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Thank you for your Audience!

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Abstract

Among existing privacy attacks on the gradient of neural networks, data reconstruction attack, which reverse engineers the training batch from the gradient, poses a severe threat on the private training data. Despite its empirical success on large architectures and small training batches, unstable reconstruction accuracy is also observed when a smaller architecture or a larger batch is under attack. Due to the weak interpretability of existing learning-based attacks, there is little known on

For more details, welcome to follow our paper.



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