

# Refurbish Your Training Data: Reusing Partially Augmented Samples for Faster Deep Neural Network Training

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# DNN Training Pipeline

DNN Training = Data Preparation + Gradient Computation

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- Data read and preprocessing
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- Forward and backward operations
- On DL accelerators (e.g., GPU, TPU)

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DNN Training = **Data Preparation** + Gradient Computation

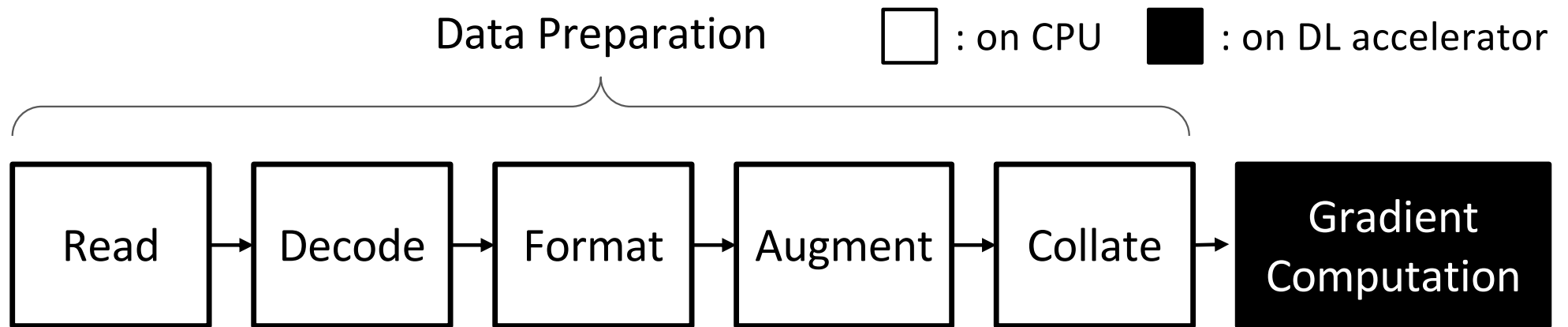
- Data read and preprocessing
- On CPU

**Bottleneck!**

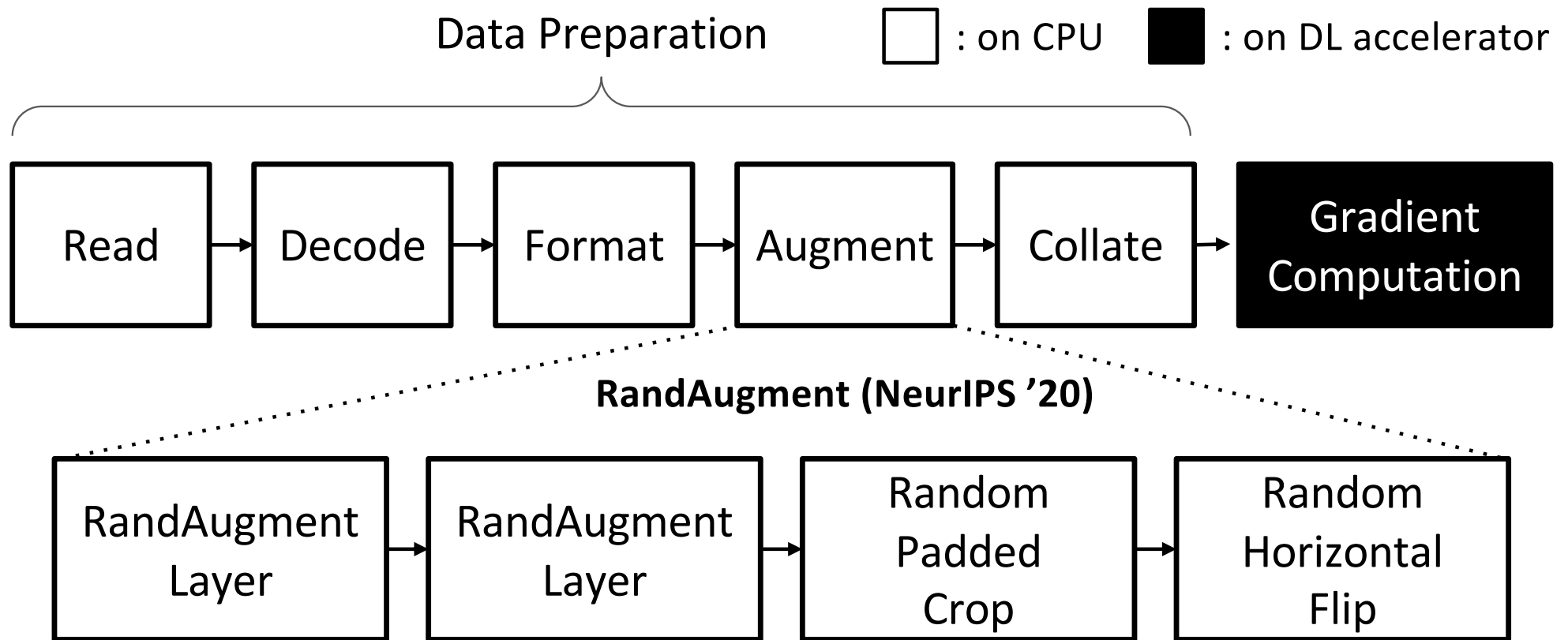
- Forward and backward operations
- On DL accelerators (e.g., GPU, TPU)

**Getting faster: NVIDIA A100, Google TPU v3, ...**

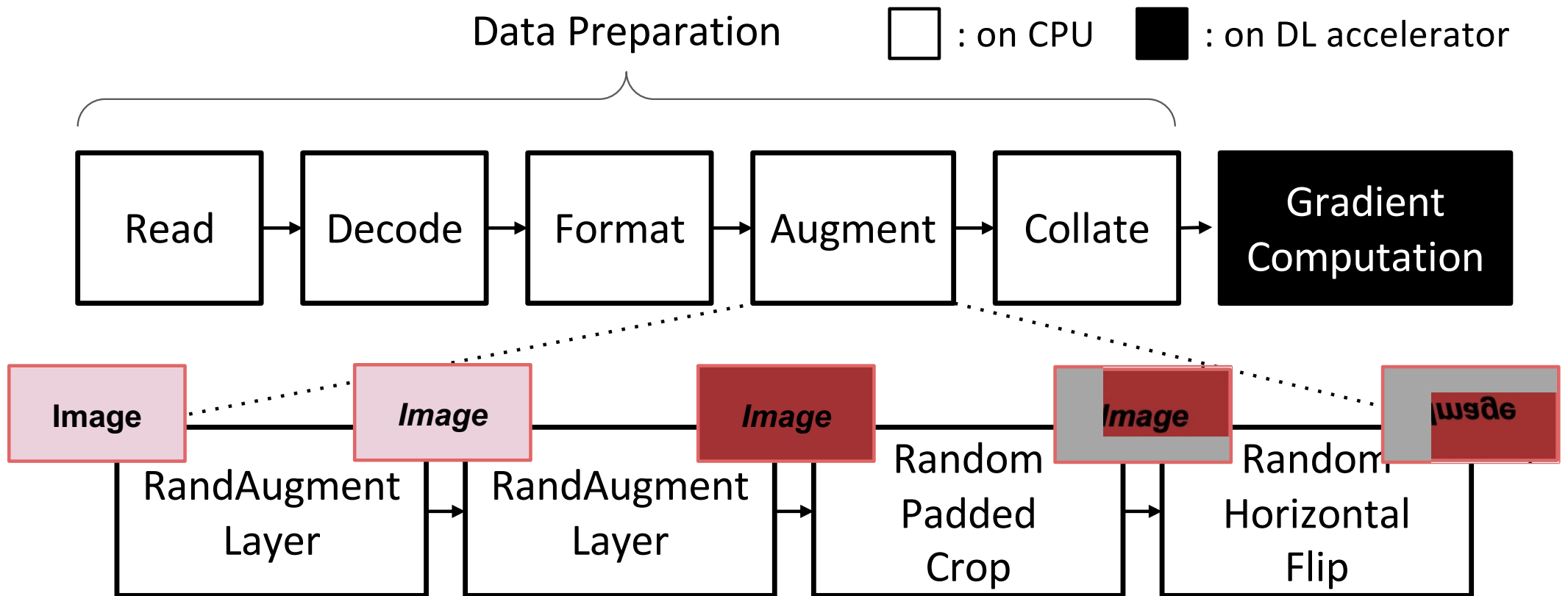
# DNN Training Pipeline



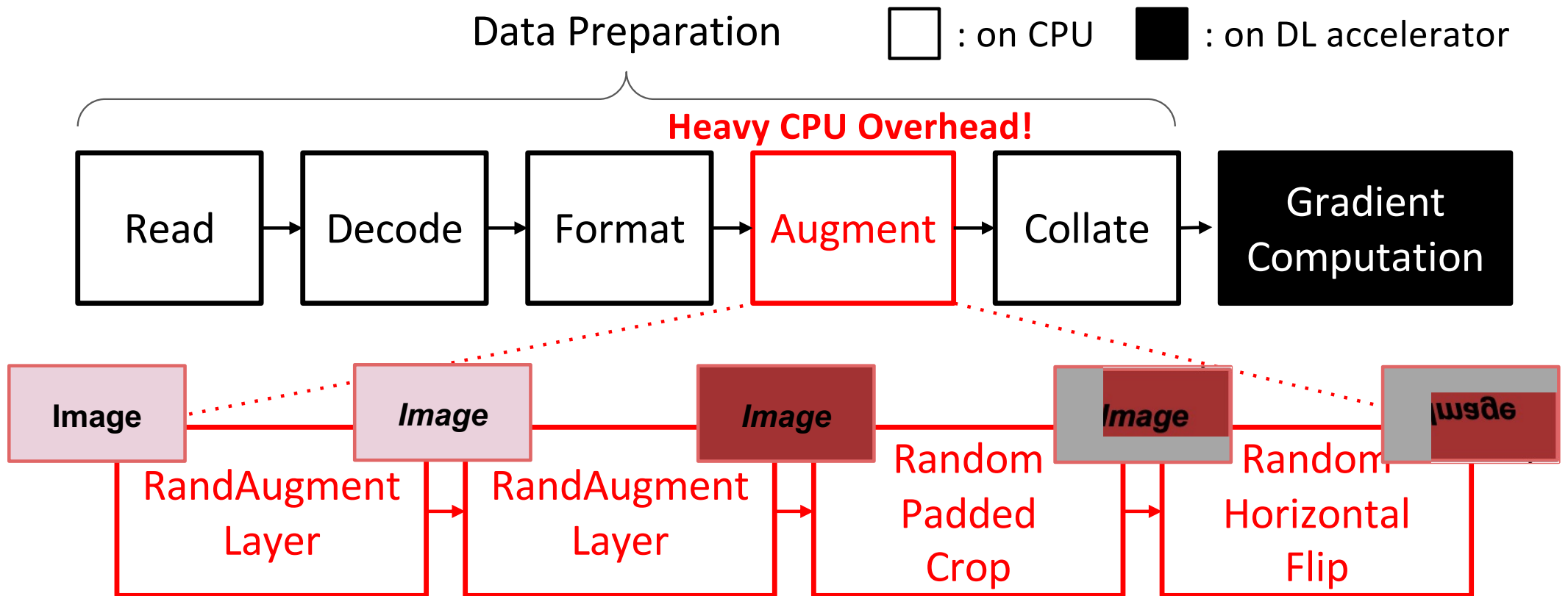
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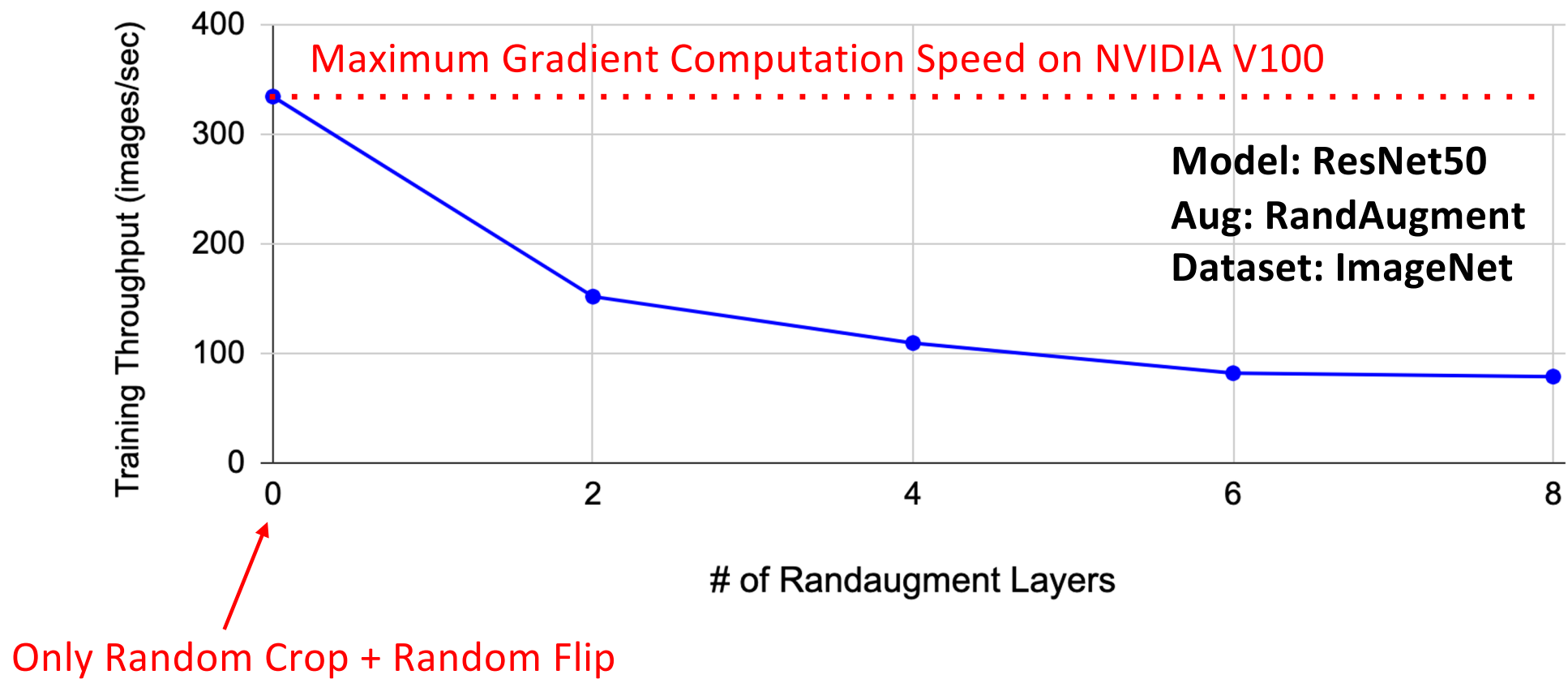
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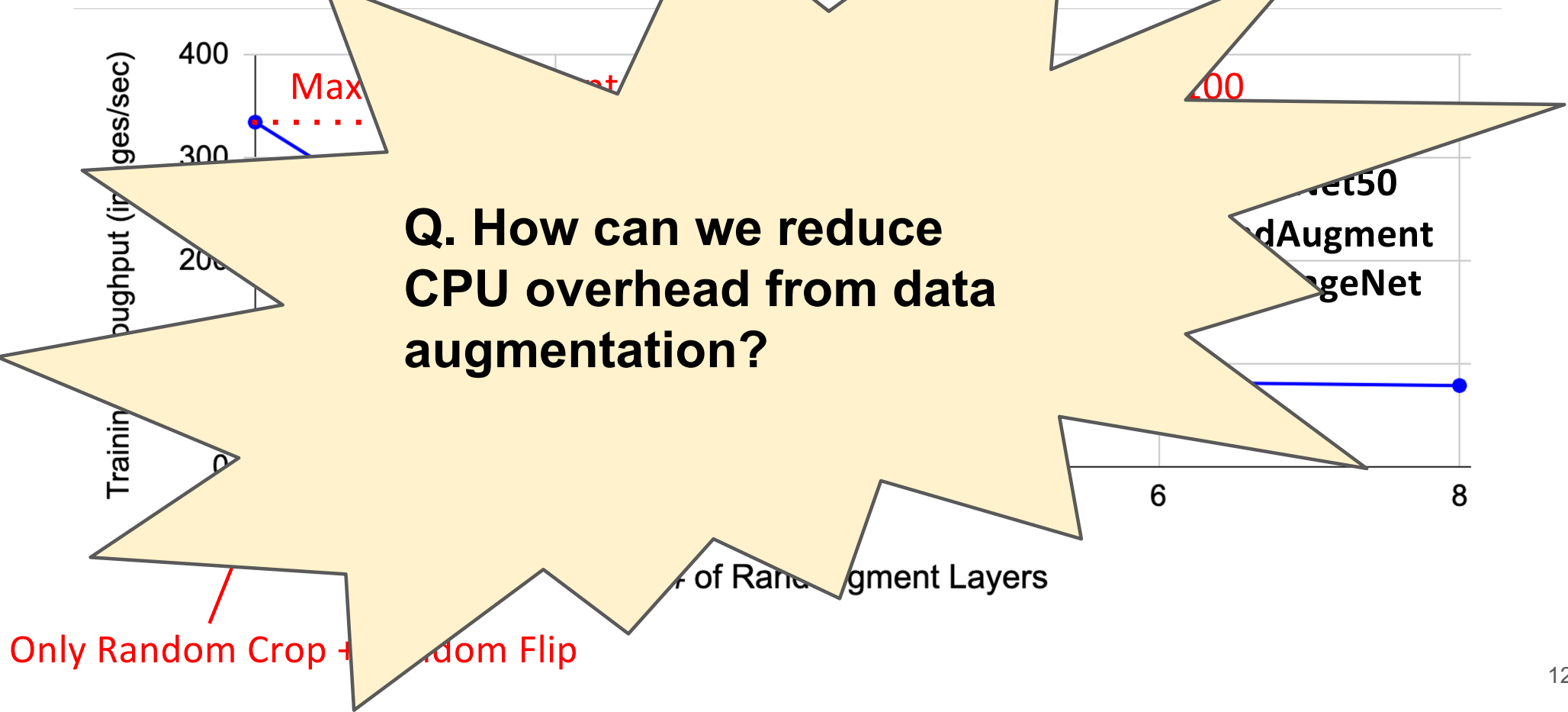
# Overhead of Data Augmentation

- Investigate the impact of data augmentation overhead
- Workload: Training ResNet50 on ImageNet with RandAugment
  - Configuration: # of RandAugment Layers
- Environment: One NVIDIA V100 GPU with four physical CPU Cores
  - Same CPU-GPU ratio as cloud GPU VMs such as AWS P3 and GCP N1 instances

# Overhead of Data Augmentation



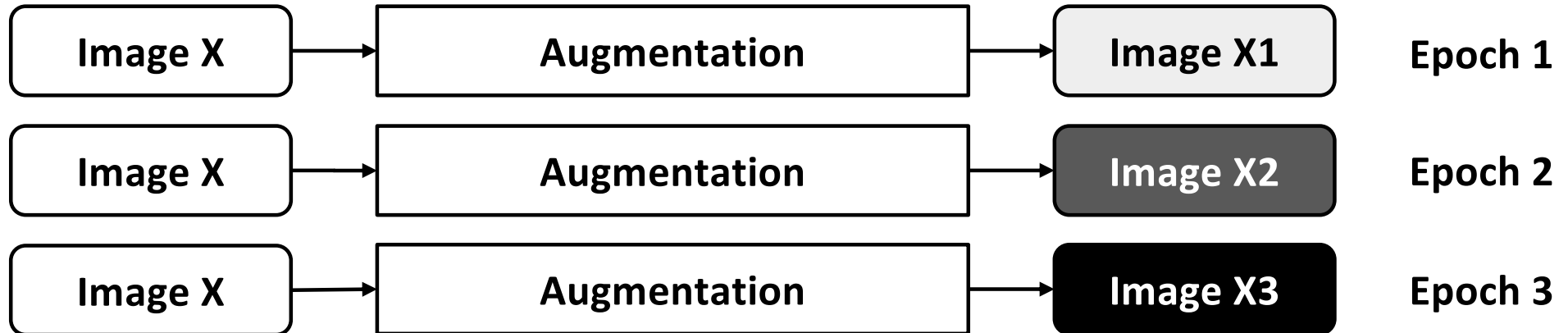
## Overhead of Data Augmentation



## Existing Approach: Data Echoing

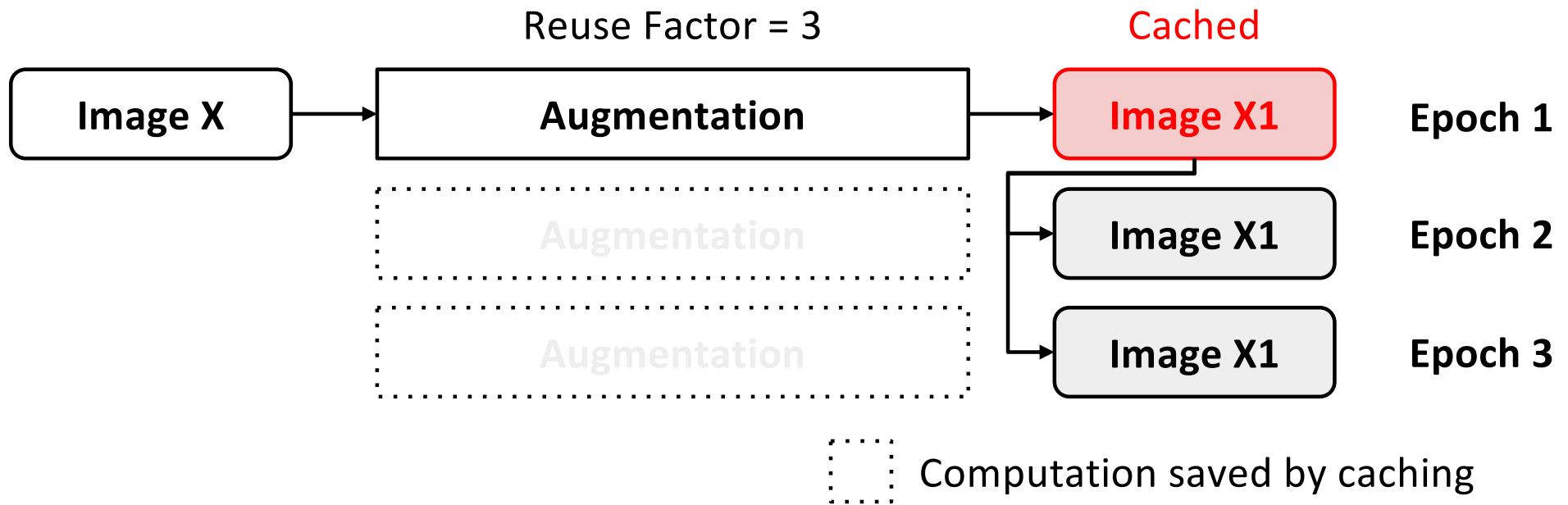
- Data echoing (arXiv '20, NeurIPS '20): Cache & reuse previously materialized samples
- Useful for training tasks with slow I/O
  - e.g., Training data on remote storage

# Standard Training



# Data Echoing

**Problem:** Sample diversity decreases to a great degree.  
-> Low generalization of trained models

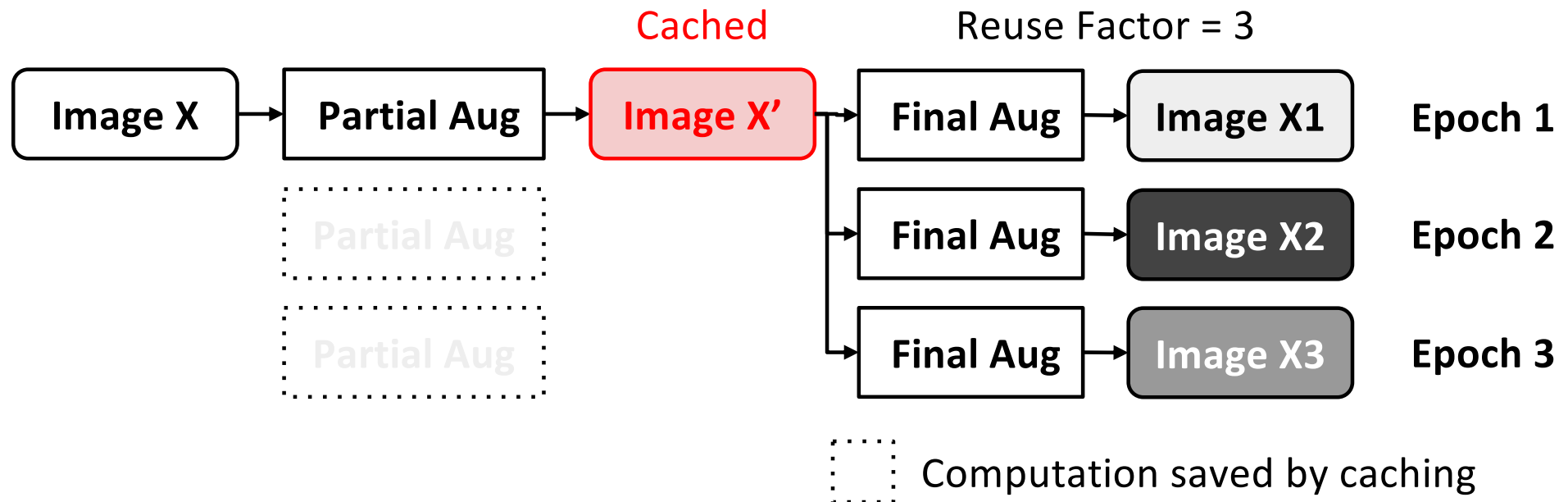


# Contents

- Background & Motivation
- **Data Refurbishing**
- Revamper
- Evaluation

## Our Approach: Data Refurbishing

**Solution:** Cache & reuse *partially augmented samples* by splitting augmentation pipelines



# Analysis on Sample Diversity

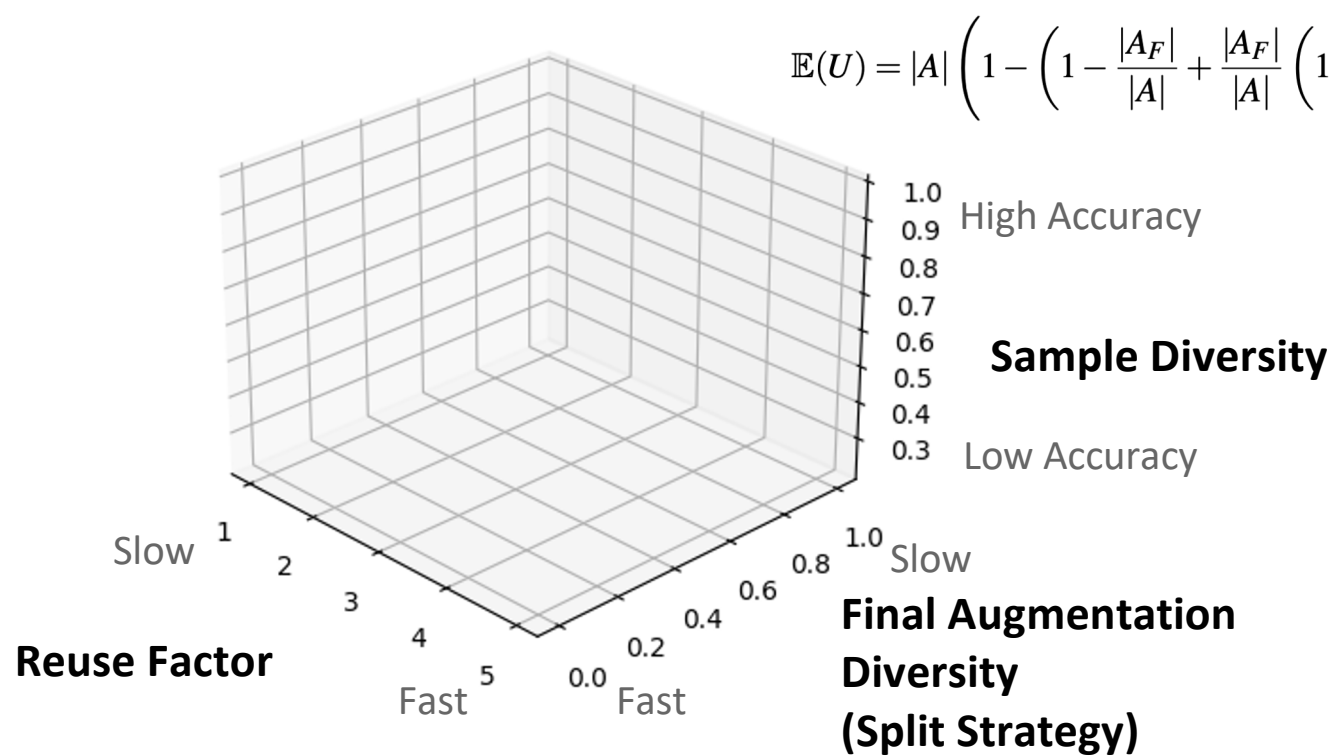
- Notations

- Given a sample,
  - $U$  (Sample Diversity): # of unique augmented samples during training
  - $|A|$  (Augmentation Diversity): # of possible unique augmented samples by an augmentation pipeline  $A$
  - $|A_F|$ : The augmentation diversity of the final augmentation
- $r$  (Reuse Factor): # of reuses for each cached sample
- $k$ : The total number of training epochs

$$\mathbb{E}(U) = |A| \left( 1 - \left( 1 - \frac{|A_F|}{|A|} + \frac{|A_F|}{|A|} \left( 1 - \frac{1}{|A_F|} \right)^r \right)^{\frac{k}{r}} \right)$$

# Analysis on Sample Diversity

**Aug: RandAugment**  
**k (# of epochs) = 300**



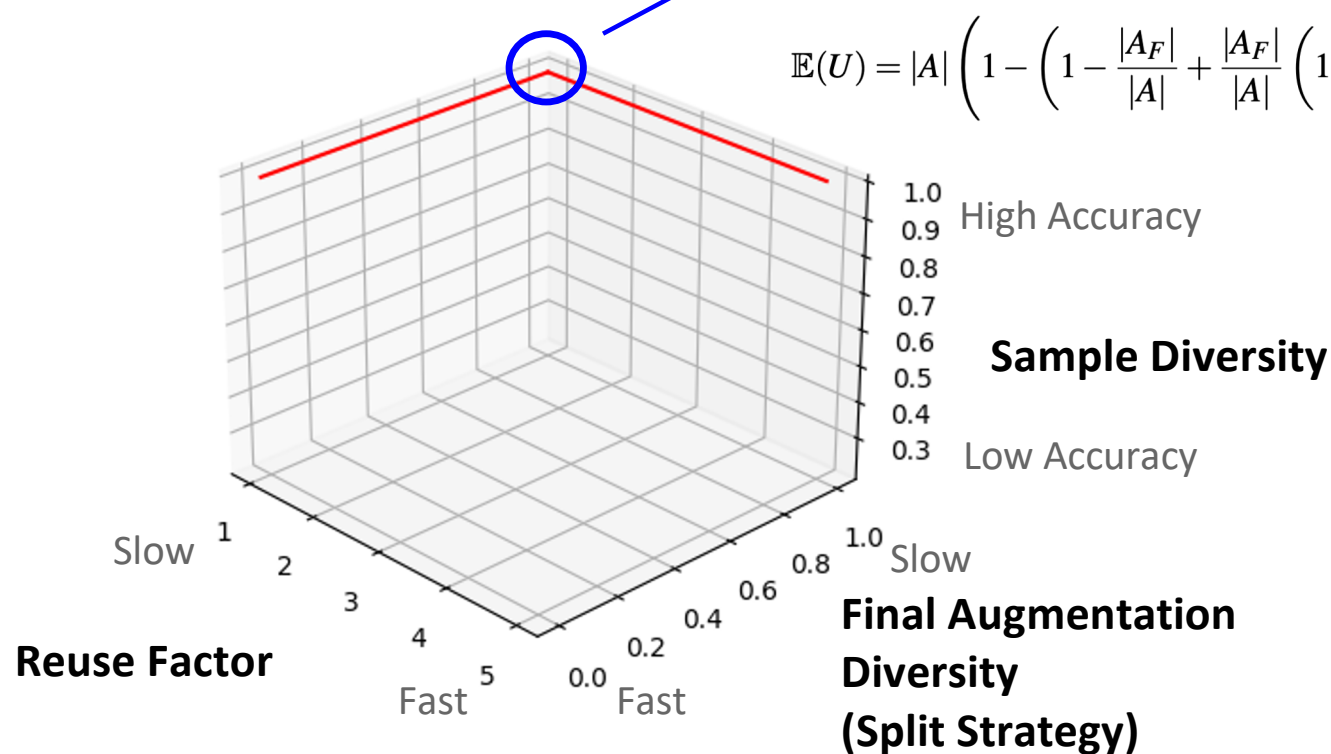
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## Case #1: Standard Training

$$|A_F| = |A| \text{ or } r = 1$$

Aug: RandAugment  
k (# of epochs) = 300

High sample diversity  
but low throughput

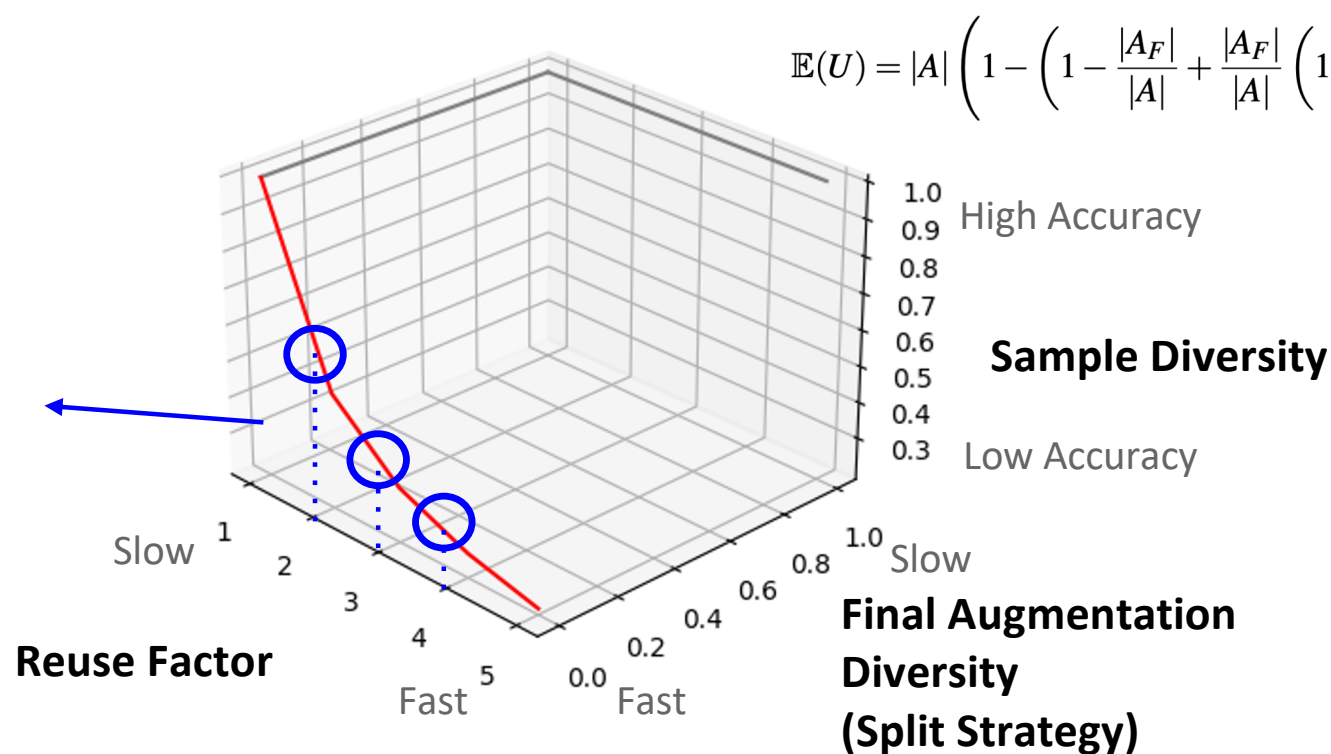


## Case #2: Data Echoing

$$|A_F| = 1 \text{ and } r > 1$$

Aug: RandAugment  
k (# of epochs) = 300

High throughput but  
low sample diversity



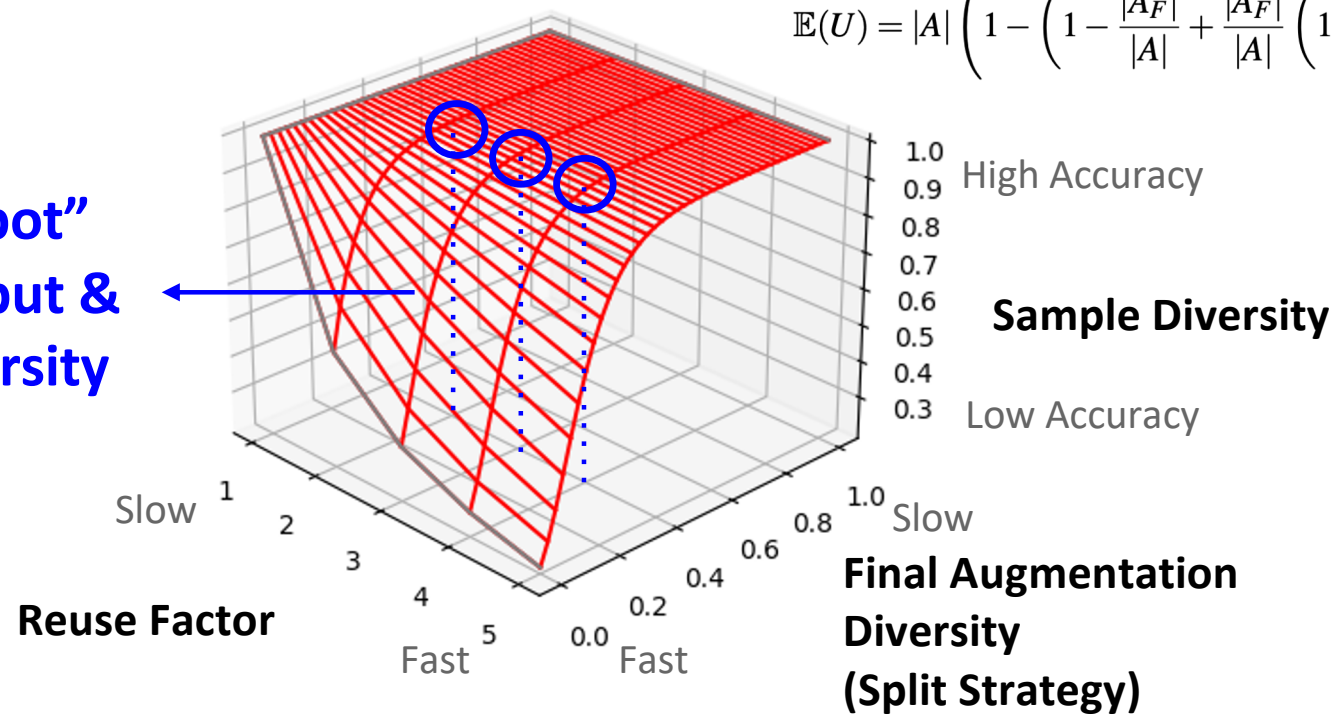
## Case #3: Data Refurbishing

$$1 < |A_F| < |A| \text{ and } r > 1$$

Aug: RandAugment

k (# of epochs) = 300

Exploit “sweet spot”  
=> High throughput &  
high sample diversity



## Case #3: Data Refurbishing

$$1 < |A_F| < |A| \text{ and } r > 1$$

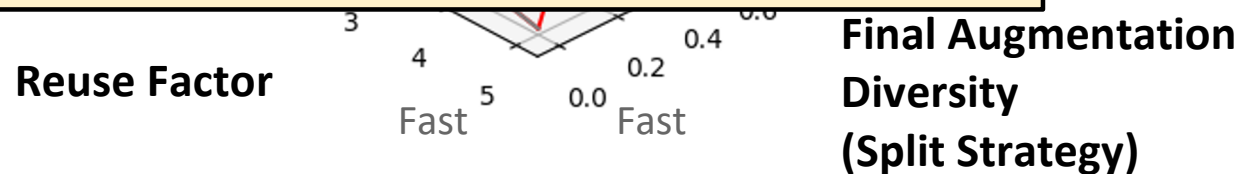
Aug: RandAugment  
k (# of epochs) = 300

Exploit “sweet spot”  
=> High throughput  
high sample diversity

### Good Split Strategy

1. Final augmentation has “enough” diversity
2. Final augmentation has low computation overhead

$$\mathbb{E}(U) = |A| \left( 1 - \left( 1 - \frac{|A_F|}{|A|} + \frac{|A_F|}{|A|} \left( 1 - \frac{1}{|A_F|} \right)^r \right)^{\frac{k}{r}} \right)$$



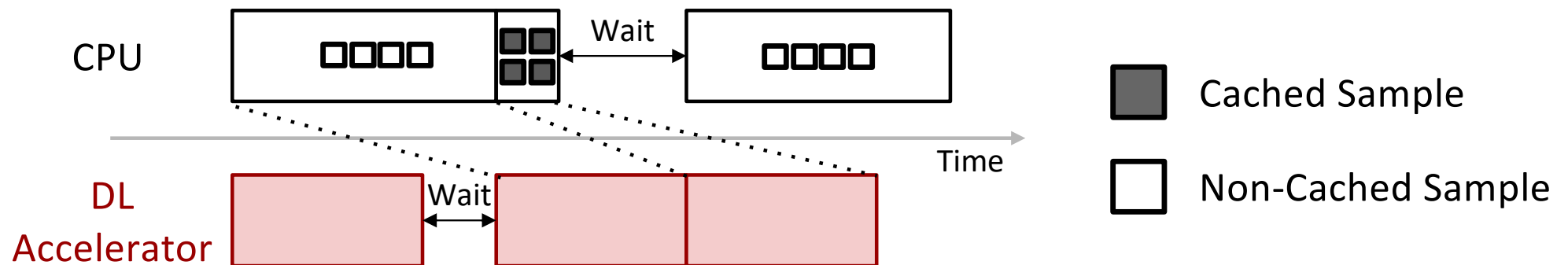
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## Challenge: Inconsistent Batch Time

- Within a mini-batch,
  - CPU processing time fluctuates according to the # of cache misses
  - Gradient computation time on DL accelerator remains the same

=> Poor computation overlap



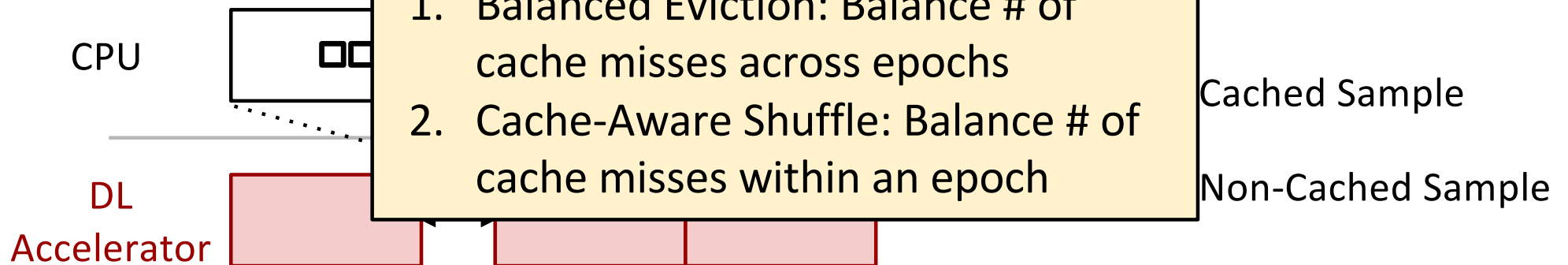
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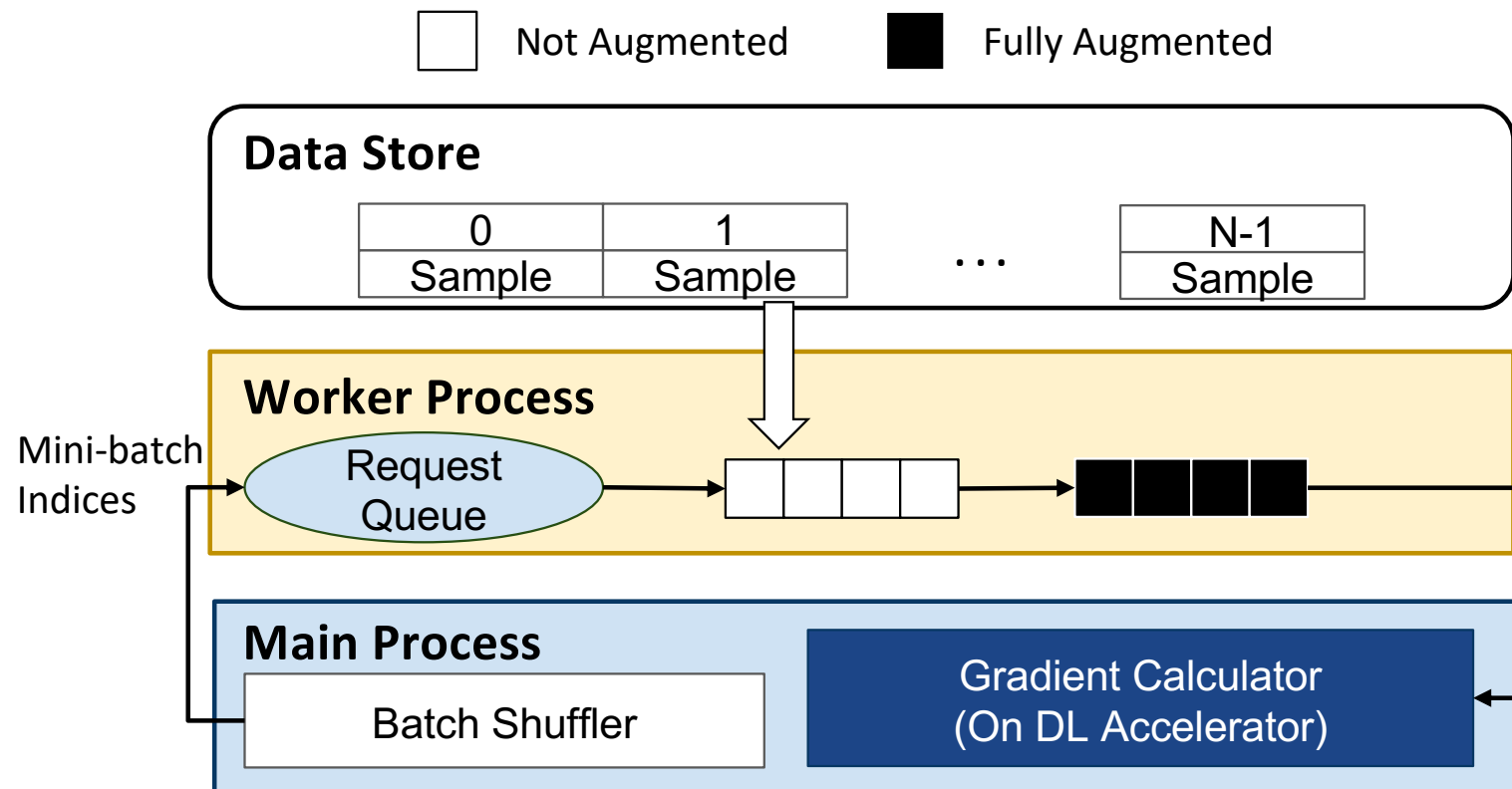
=> Poor computation

### Solution: Revamper

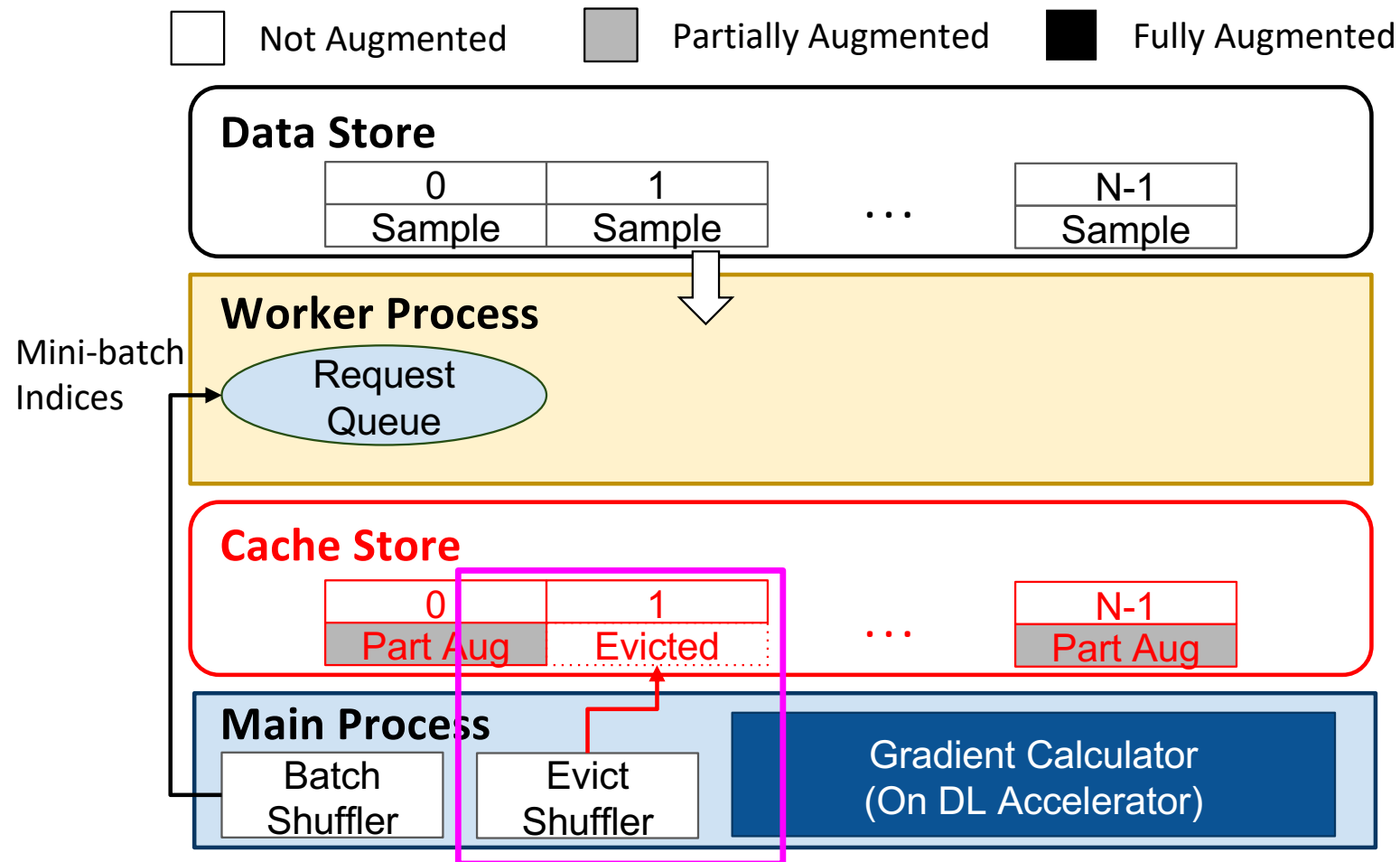
1. Balanced Eviction: Balance # of cache misses across epochs
2. Cache-Aware Shuffle: Balance # of cache misses within an epoch



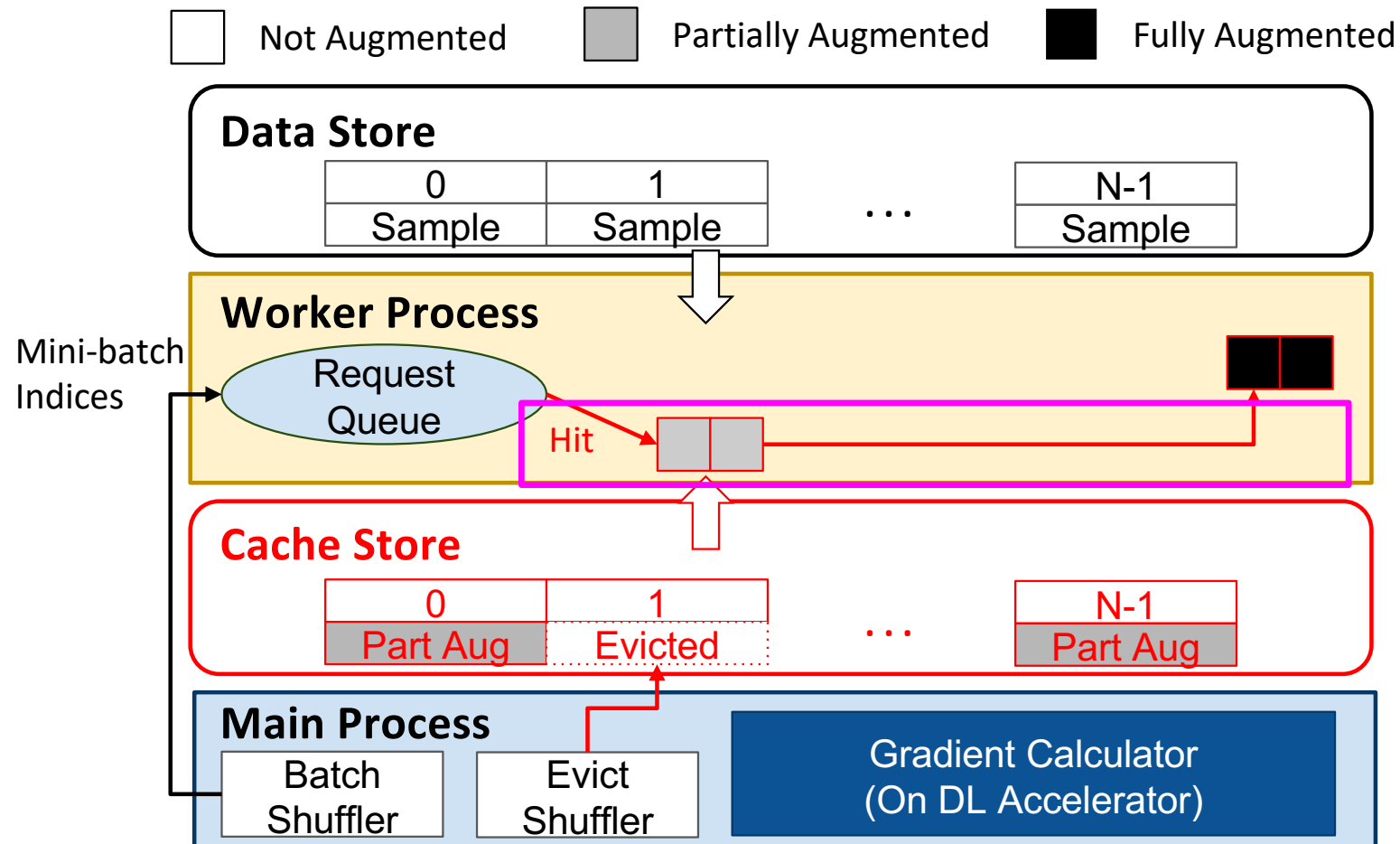
# PyTorch Dataloader



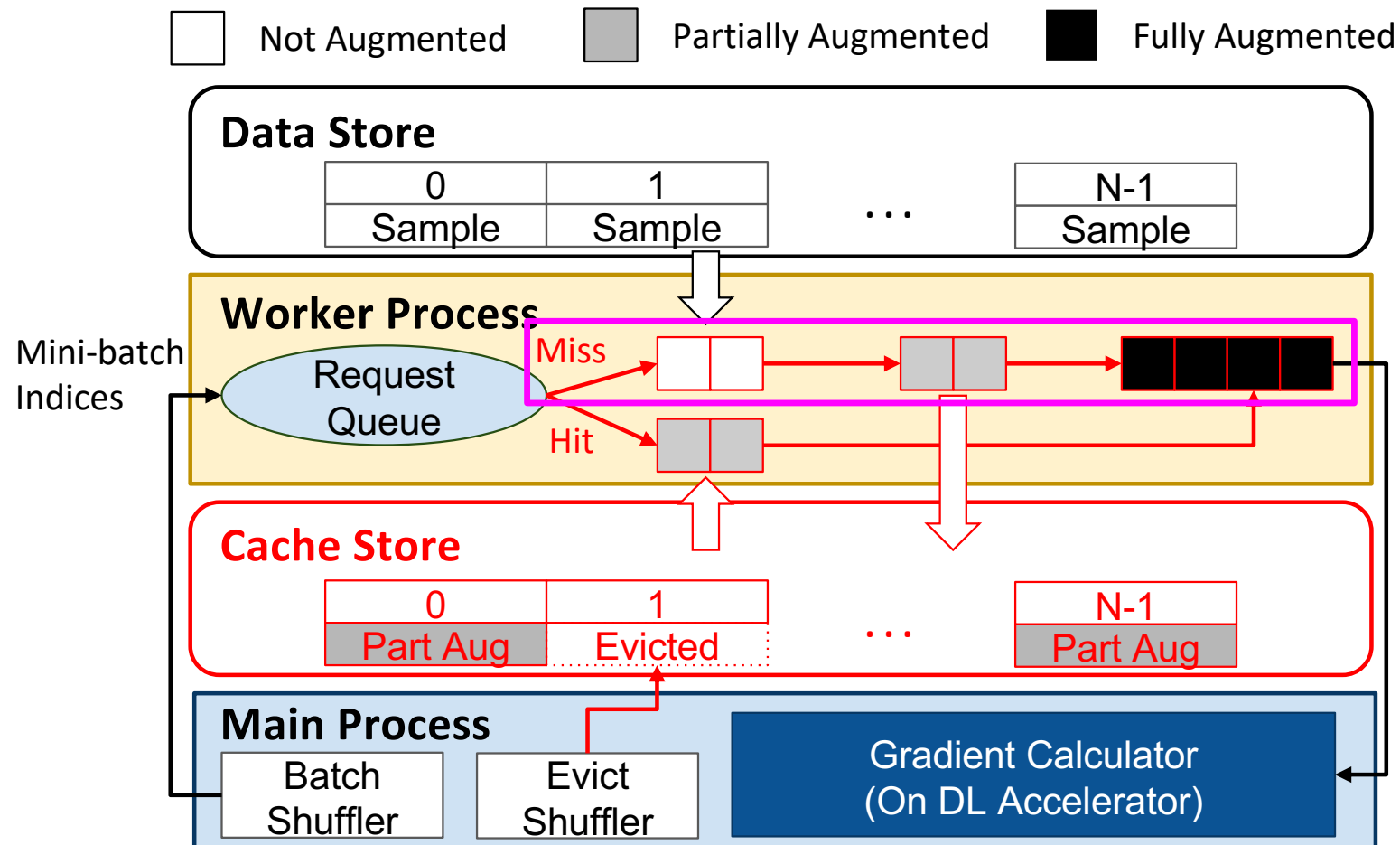
# Revamper



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# Balanced Eviction

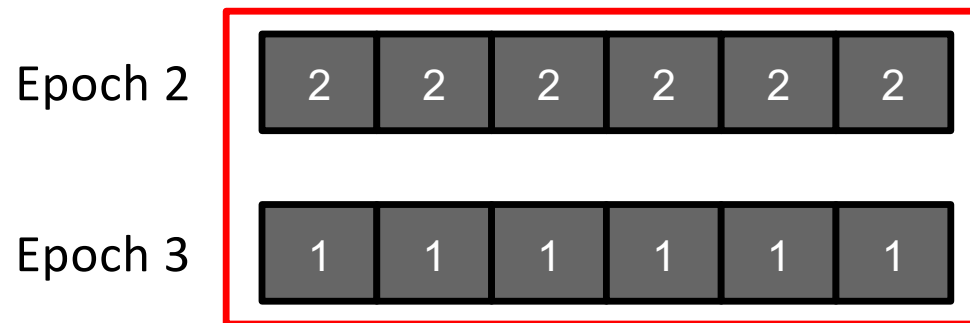
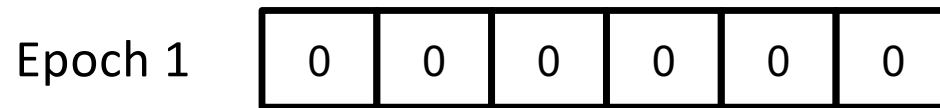
Reuse Factor = 3



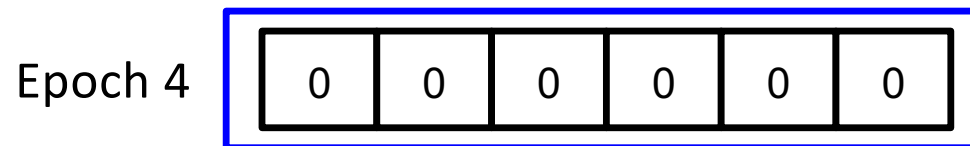
Cached Sample



Non-Cached Sample



Fast: Possibly bottlenecked  
by DL accelerators



Slow: Possibly bottlenecked  
by CPU

Naive (Reference Count)

# Balanced Eviction

Reuse Factor = 3

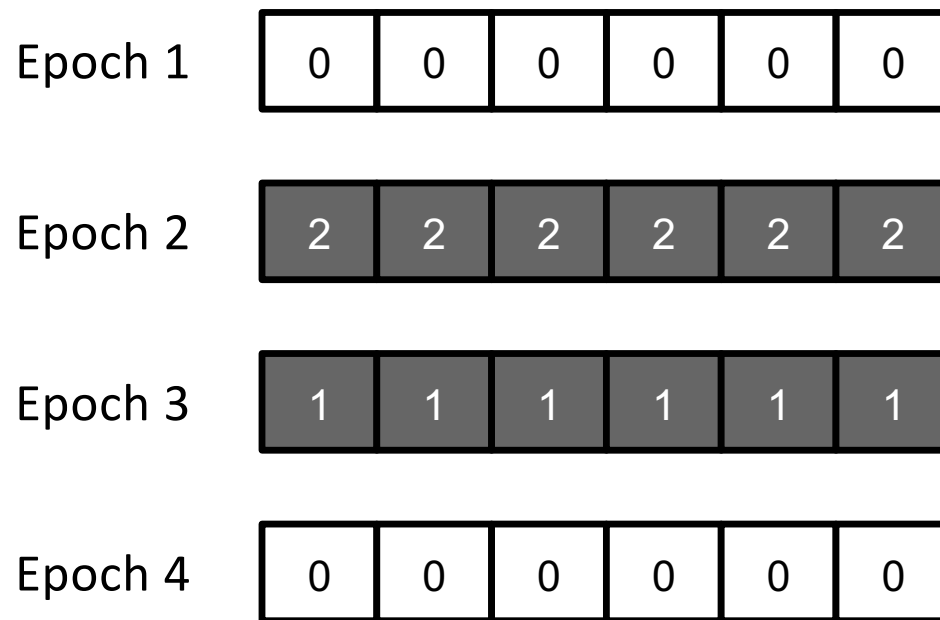


Cached Sample



Non-Cached Sample

# evicted samples:  $6/3 = 2$



Naive (Reference Count)



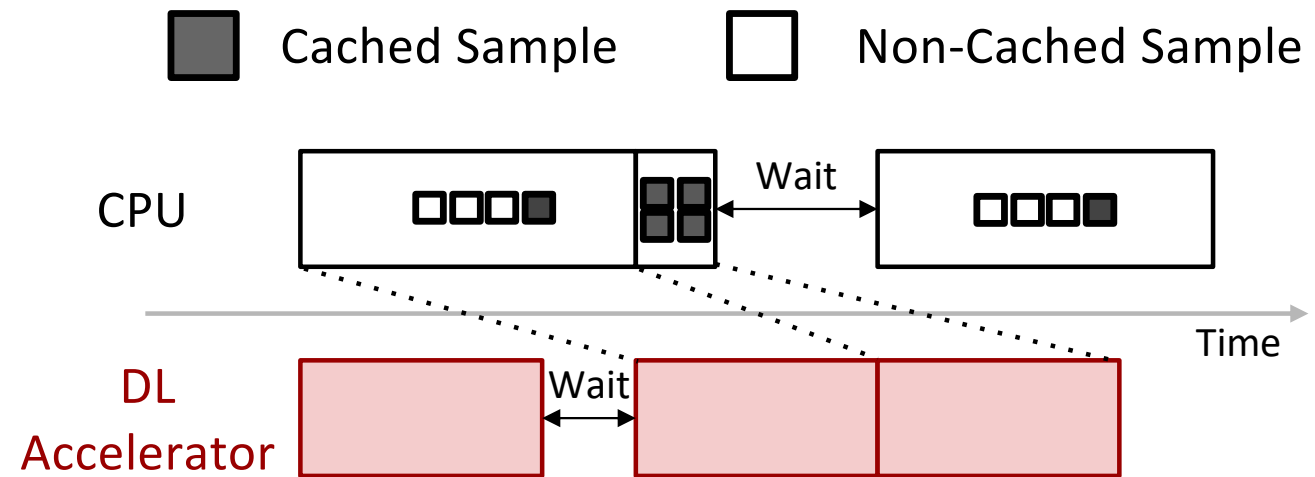
Balanced Eviction

# Cache-Aware Shuffle

Batch Size = 4

Reuse Factor = 2

Random Shuffle



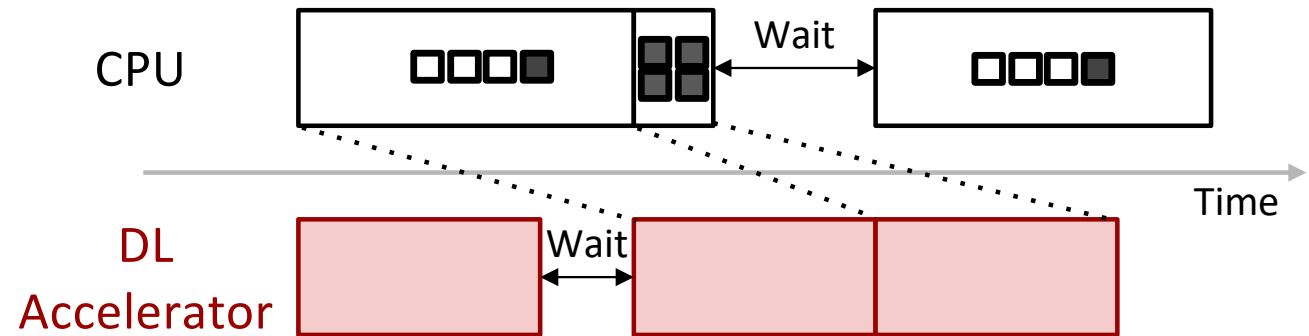
# Cache-Aware Shuffle

Batch Size = 4

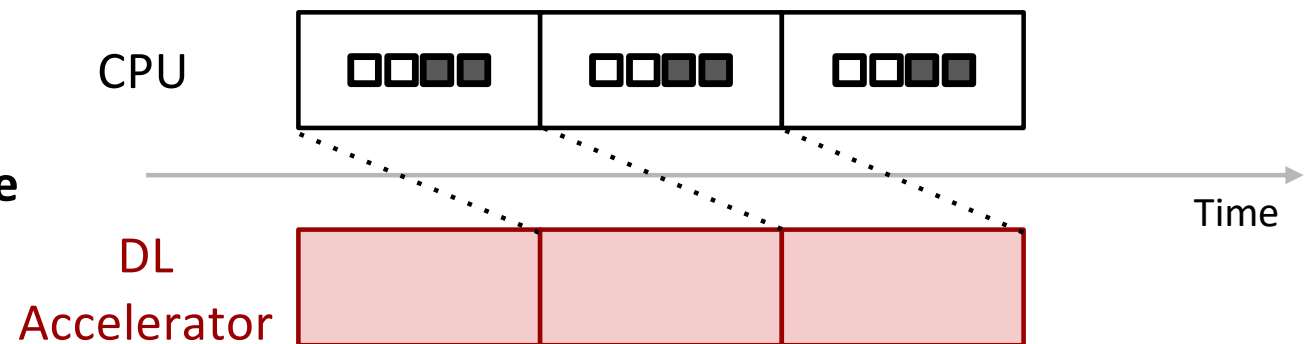
Reuse Factor = 2



## Random Shuffle



## Cache-Aware Shuffle



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- **Evaluation**

# Implementation

- Implemented in 2000+ lines of Python code based on PyTorch 1.6
- Identical interface to the PyTorch dataloader except for some additional parameters
  - e.g., reuse factor and split strategy

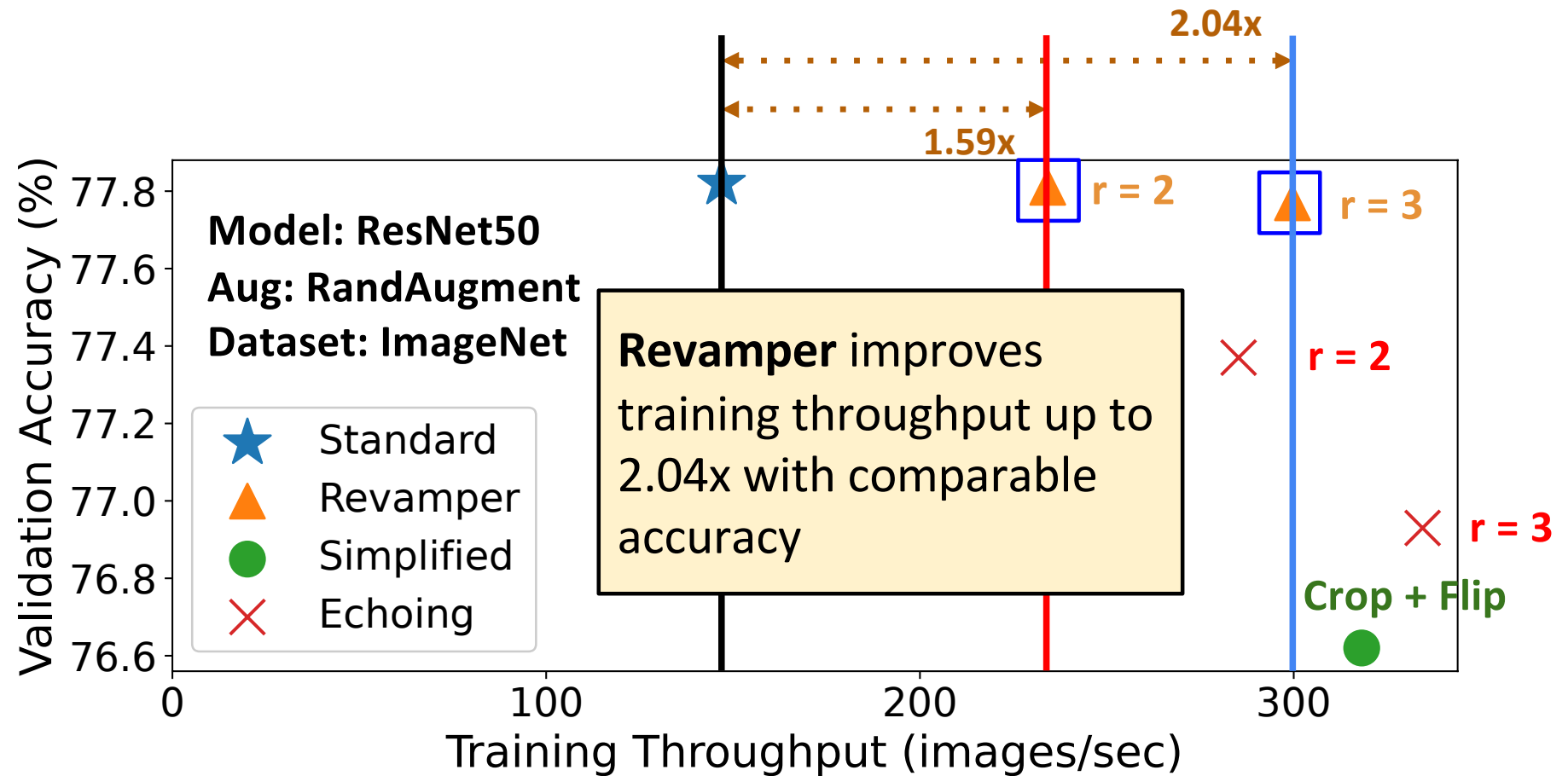
## Evaluation: Environments

- Training server specification
  - CPU: Intel Xeon E5-2695v4 (18 cores, 2.10GHz, 45MB Cache)
  - RAM: 256GB DRAM
  - GPU: NVIDIA V100
  - Disk: Samsung 970 Pro 1TB NVMe SSDs
- We adjust CPU-GPU ratios using a Docker container (Default = 4:1)
- Workload: Image Classification

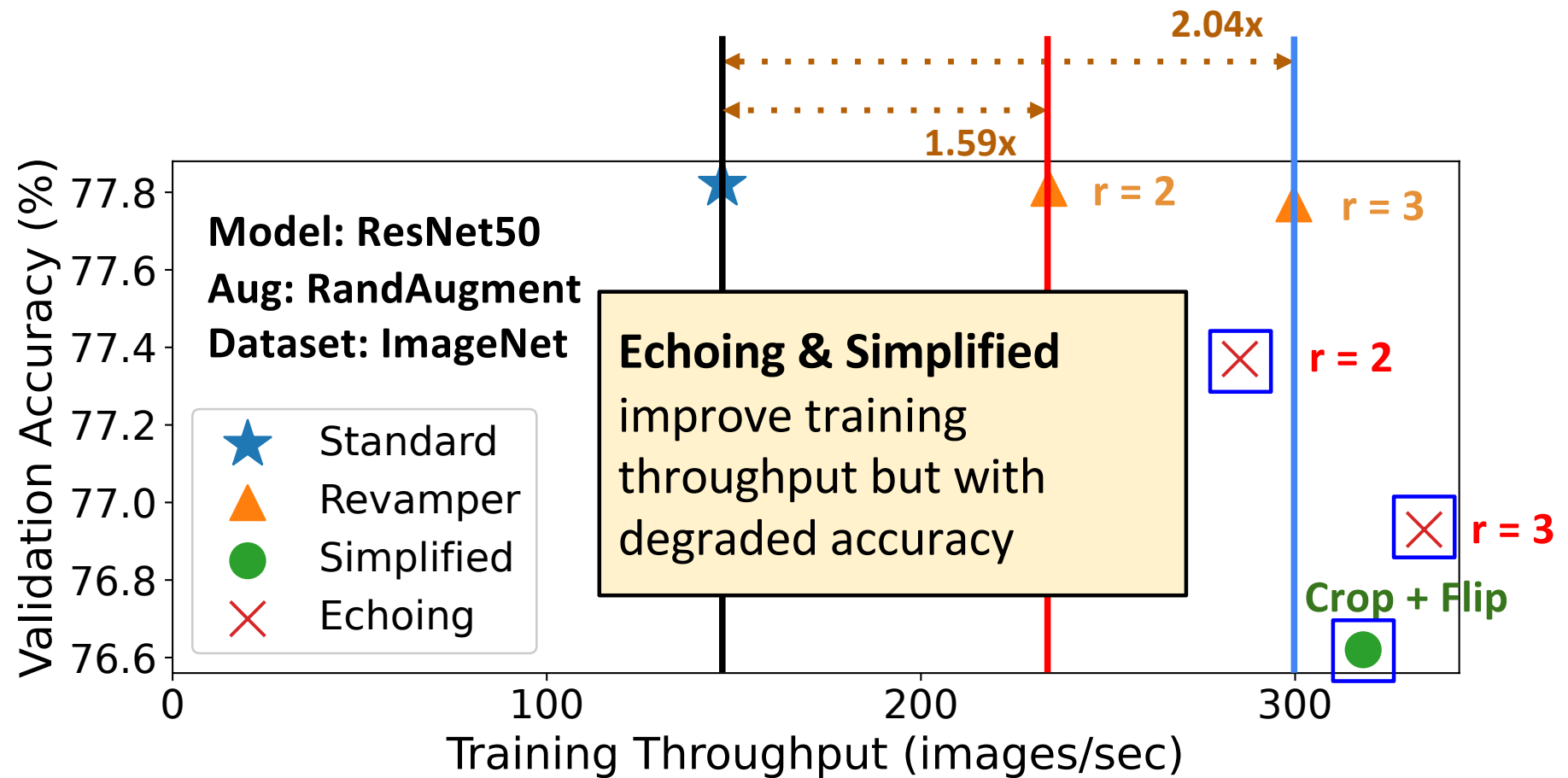
## Evaluation: Baselines

- Standard: DNN training without adopting data reusing mechanism
- Data Echoing: Cache & reuse fully augmented samples
- Simplified: Simply removing one or more transformation layers
- Same hyperparameters for all the training settings
  - Revamper does not require additional hyperparameter tuning

## Evaluation: Accuracy & Throughput

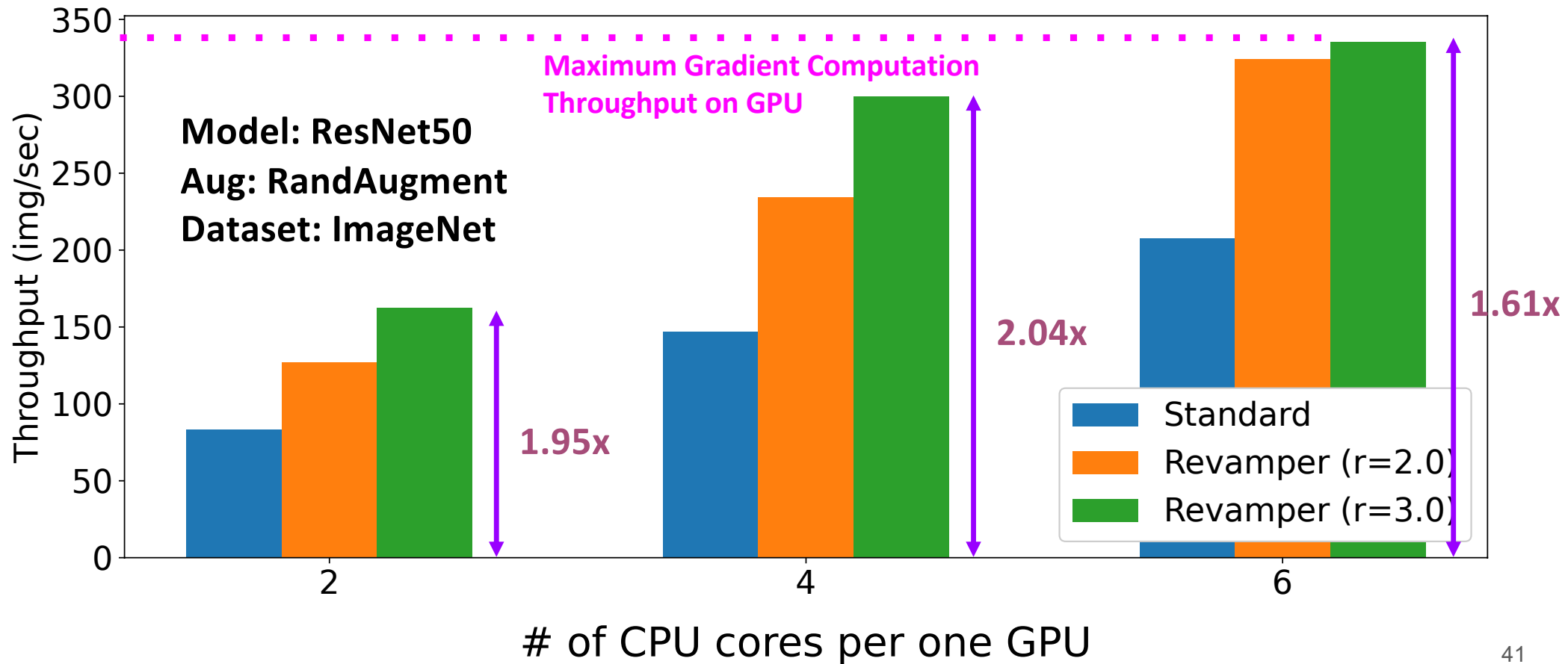


## Evaluation: Accuracy & Throughput



## Evaluation: CPU-GPU Ratio

Fewer CPUs -> Bigger Thp Gain



## Conclusion

- **Data refurbishing** is a new intermediate data caching technique for DNN training that accelerates data augmentation while preserving diversity of augmented samples.
- **Revamper** realizes data refurbishing by maximizing computation overlap between CPU and DL accelerators with carefully-designed cache eviction and shuffle strategies.
- Revamper improves training throughput of DNN models by **1.03x-2.04x** while maintaining comparable accuracy.