# LiveTag: Sensing Human-Object Interaction Through Passive Chipless WiFi Tags

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## **Sensing Human-Object Interaction**

#### Human activity involves interaction with physical objects

- Inferring human activities
- Using objects as command-and-control interface



# Can we detect touch interaction on everyday objects?

## **Design Goals**



# LiveTag Basics

- Chipless, passive WiFi tag
- Attached to objects
- Serve as touch interfaces
- Detectable by WiFi devices



#### A Smart Home Enabled by LiveTag



## LiveTag Basics



# LiveTag Solution

#### • Tag design

- Creating WiFi detectable feature with resonator
- Enabling multiple touch points on the tag

#### • Detecting tags and touches with WiFi

- Combating multipath fading with beamforming
- Suppressing self-interference
- Robust touch detection mechanism

#### **Creating WiFi Detectable Features**



- WiFi signal PSD "modulated" by resonators
- Each resonator creates a notch at a certain frequency
- Notch frequencies serve as tag signature

## **Enabling Multiple Touch Points**

• Resonators are "detuned" when touched



• Multiple touch points on a single tag



# Optimizing Tag Structure in LiveTag

• Tag frequency response determined by resonator shape



- Optimize shape parameters to obtain desired prosperities
  - Notch center frequency
  - Deep & narrow notches
  - Independent notches

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#### Extracting Tag Signature with WiFi Devices

- WiFi transmitter sends packets across all WiFi channels
- Receiver extracts CSI on each channel
- Stiches CSI to obtain complete PSD



- Multipath facing also creates deep frequency notches
- Signal travels through direct and multiple reflection paths
- Constructively/Destructively combined depending on path lengths
- Properties of fading notches depend on reflectors



- Solution: Let signal hit different reflectors
  - Fading notches varies, but tag notches persist
- Use multiple antennas to steer beam towards different directions
  - Beamforming creates directional transmission "beams"



Beam	<b>Detected Notches</b>
1	<i>f</i> <sub>1</sub> , <i>f</i> <sub>2</sub>

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2	$f_1, f_2, f_3$
3	<i>f</i> <sub>2</sub> , <i>f</i> <sub>4</sub>

#### Notch at $f_2$ is consistent: We find a tag notch!

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- Measure Line-of-Sight (LOS) direction
- WiFi transmitter creates a null along LOS direction



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#### **Robust Touch Detection**

- WiFi receiver monitors the change at each notch position
- Constant false alarm rate detection

$$F(x) = 1 - \exp(-\frac{x^2}{4\rho^2})$$
$$P_f(V_{th}) = \exp(-\frac{V_{th}^2}{4\rho^2})$$

- Improving detection robustness
  - Multiple redundant resonators with different notch frequencies
  - Multiple sets of CSI

#### Implementation

- WARP software defined radios
- Linux PCs with CSI-Tool



## **Key Evaluation Results**

Detection Accuracy

	Tag Detection	<b>Touch Detection</b>
Accuracy	> 95%	> 95%

• Detection Range

	Tx-to-Tag	Tag-to-Rx
Range	4-5 m	0.4-0.5 m

#### **Control Panel for Smart Home**



#### Water Level Detector





# Summary

- Bringing remote touch sensing to passive objects
- Passive, chipless WiFi tag
- Future Work
  - Tag manufacture
  - Extending detection range

# **Questions?**

